# Vihang Agarwal

Machine Learning Engineer

(929) 461 7976



vihang@umich.edu



/in/vihangagarwal/



vihang-ag

### Education -

MS, Electrical Engineering and Computer Science (GPA: 3.82) Specialization: Computer Vision University of Michigan May 2020 | Ann Arbor, MI, USA

BTech, Mechanical Engineering

Minor: Computer Science Indian Institute of Technology, Kanpur 2014 - 2018 | Kanpur, India

#### Certifications

**Robotics Mobility** University of Pennsylvania

**Robotics Computational Motion Plan-**

University of Pennsylvania

## Technical Skills ——

- C++ C Python Matlab Julia
- Pytorch TensorFlow SQL Java
- OpenCV Scikit-learn Pandas
- keras scipy NumPy Jupyter
- Docker git ROS Simulink
- AutoCAD Mathematica Flask

#### Course Work -

Deep Learning and Neural Networks

Advanced Machine Learning

Computer Vision

Natural Language Processing

**Probabilistic Mobile Robotics** 

Approximation Algorithms

Human-AI Interaction/Crowdsourcing

**Continous Optimization Methods** 

Data Structures and Algorithms

**Fundamentals of Computing** 

**Probability and Random Processes** 

#### **Experience**

May 2019 -**Amazon Go** Aug 2019

**Applied Scientist | Computer Vision, C++, Pytorch** 

 Enhanced system accuracy by over 2% by improving Image Classification through utilizing temporal correlations. The designed algorithm (C++) was implemented in the product life-cycle

 Leveraged quantization-aware training to deploy Object Detection models on resource constrained hardware while minimizing potential quality degradation

Sep 2019 -University of Michigan, Medicine Present Research Assistant | Computer Vision, Medical Imaging

Kanpur, India

Boston, MA

• Achieved high resolution MRI reconstruction in Pytorch through the

use of computationally efficient Sparse Attention

• Reduced MRI scan times upto 10x by designing and training Cascaded Attention U-net for reconstruction of under-sampled MRI

Sep 2019 -Amazon Alexa Prize Challenge 2020 Apr 2019 Research Assistant | NLP, Conversational AI, Python

> · Executed Batch RL based policy learning for effective topic transitions and dialogue flow as a Docker container [Link]

> Achieved Perplexity of 18.02 by designing a Heirarchical response generator with GPT-2 fine-tuned on topical data-sets

Apr 2018 -**Transpacks Technologies** Jul 2018 **Software Engineer | Image Reconstruction, Python** 

 Employed an ensemble of Denoising Auto-encoder based neural network and gradient based Image Processing in Pytorch to restore distorted QR code images

• Improved model True Positive rate by  $\sim 20\%$  over conventional QR readers while maintaining robustness under extreme lighting conditions, distortions, different surface geometries and noise

#### Research

May 2017 -Semantic Segmentation guided SLAM Jul 2017

Mentored by Prof. Farshad Khorrami, Robotics Research Lab

 Obtained robust robot paths in C++ by implementing Fast SLAM based on **Semantic Segmentation** (ENet)

· Alleviated drifts due to translation and rotation errors by fusing sensor data from LIDAR, Odometry, and Monocular Camera

Sep 2019 -**3D Visual Scene Understanding** 

University of Michigan

**New York University** 

Dec 2019 Mentored by Prof. David Fouhey, Fouhey AI Lab

• Estimated Depth, Normal and Occlusion Edges on NYUv2 dataset by implementing **ResNet-DenseNet** network

· Studied efficient transfer learning in Pytorch by exploring task dependencies and analyzing learnt feature representations

### **Select Projects**

- PawPal: Developed a Virtual Pet-Sitter with multi pet localization and activity surveillance in Tensorflow by feature engineering Object Detection (YOLO) and Activity Recognition (C3D) augmented with geometrical relationships [git] [Link]
- Improving Traffic Flow with Deep RL: Autonomous vehicle driving in Deep Traffic Simulator by implementing Action-specific DQN and Recurrent DRQN [git] [Link]
- Large scale Video Classification: Achieved Top-1/Top-5 accuracy of 73.1%/88.8% on Kinetics-400 dataset by using a two-stream network with pre-trained Inception-Resnet and Xception module for activity recognition.
- Neural Algorithm for Artistic Style Transfer: Fused artistic styles and content from images by using Deep Convolution Networks (AlexNet and VGG-19)